



Angular Contact Ball Bearing

Ningbo Amol Machinery Co., Ltd.
Jiangsu Amol Bearing Co., Ltd.
Ningbo Amol Intl. Trade Co., Ltd.



WBW BEARING

Angular Contact Bearing covers the following three variants:



Angular contact ball bearings are non-separable bearings with a defined contact angle in the radial direction relative to the straight line that runs through the point where each ball makes contact with the inner and outer rings (see Fig. 1). Table 1 provides information on contact angles and their designated codes. In addition to radial loads, angular contact ball bearings can accommodate single direction axial loads. Since an axial load is generated from a radial force, these bearings are generally used in pairs. Table 2 shows general angular contact ball bearing characteristics, Table 3 shows information on using duplex (side by side) angular contact ball bearings, and Table 4 shows information on multiple-row angular contact ball bearings.

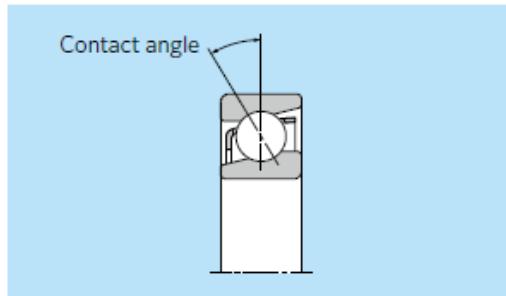


Fig. 1

Table 1 Contact angle and contact angle codes

Contact angle	15°	30°	40°
Contact angle code	C	A ¹⁾	B

1) Contact angle symbol A is omitted from part number.

Table 2 Angular contact ball bearing types and characteristics

Type	Design	Characteristics
Standard type		<ul style="list-style-type: none"> Available in bearing series 79, 70, 72, 72B, 73, and 73B. Contact angles: 30° and 40° (with B) available. Standard bearing cage type differs depending on bearing number. (see Table 5)

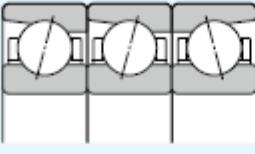
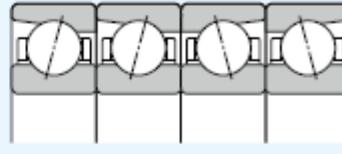
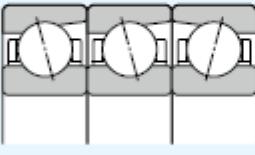
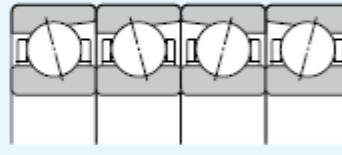
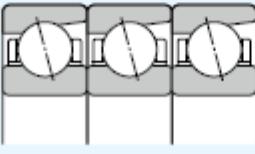
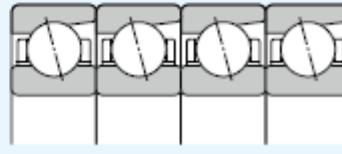
Table 3 Duplex angular contact ball bearings — types and characteristics

Duplex type	Characteristics
Back-to-back arrangement (DB)	<ul style="list-style-type: none"> Can accommodate radial loads and axial loads in either direction. Has a large distance between the acting load centers of the bearings, and therefore a large momentary force load capacity. Allowable misalignment angle is small.
Face-to-face arrangement (DF)	<ul style="list-style-type: none"> Can accommodate radial loads and axial loads in either direction. Has a smaller distance between the acting load centers of the bearings, and therefore a smaller momentary force load capacity. Has a larger allowable misalignment angle than back-to-back duplex type.
Tandem arrangement (DT)	<ul style="list-style-type: none"> Can accommodate radial loads and single direction axial loads. Axial loads are received by both bearings as a set, and therefore heavy axial loads can be accommodated.

Note: 1. Duplex angular contact ball bearings are manufactured in a set to specified clearance and preload values; therefore, they must be assembled side by side with identically numbered bearings and not be mixed with other arrangements.

2. To satisfy specified clearance and preload values, tightening must be performed until the inner ring width surfaces or outer ring width surfaces come in contact with each other.

Table 4 Combination examples of multiple-row angular contact ball bearings

Duplex type	3-row arrangement	4-row arrangement
Back-to-back arrangement	 (DBT)	 (DTBT)
Face-to-face arrangement	 (DFT)	 (DTFT)
Tandem arrangement	 (DTT)	 (DTTT)

Four-point angular contact ball bearings have a contact angle of 30° and a split inner ring. As shown in Fig. 2, when the inner and outer rings receive a radial load, the ball contacts the inner and outer rings at four points. This construction

enables a single bearing to accommodate axial loads from either direction, and when under a simple axial load or heavy axial load, the bearing relies on two contact points like ordinary bearings.

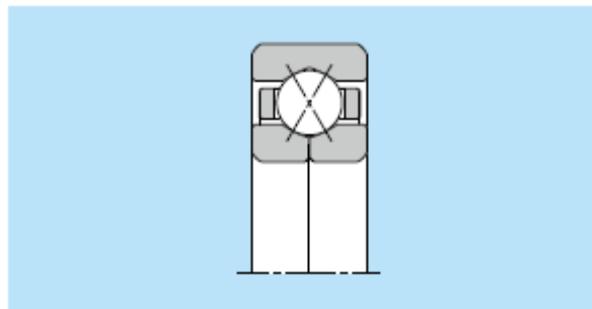


Fig. 2

Double row angular contact ball bearings have the structure of double row angular contact ball. The bearing is designed by arranging two single row angular contact bearings back-to-back in duplex (DB) to form a single bearing with a contact angle of 25° .

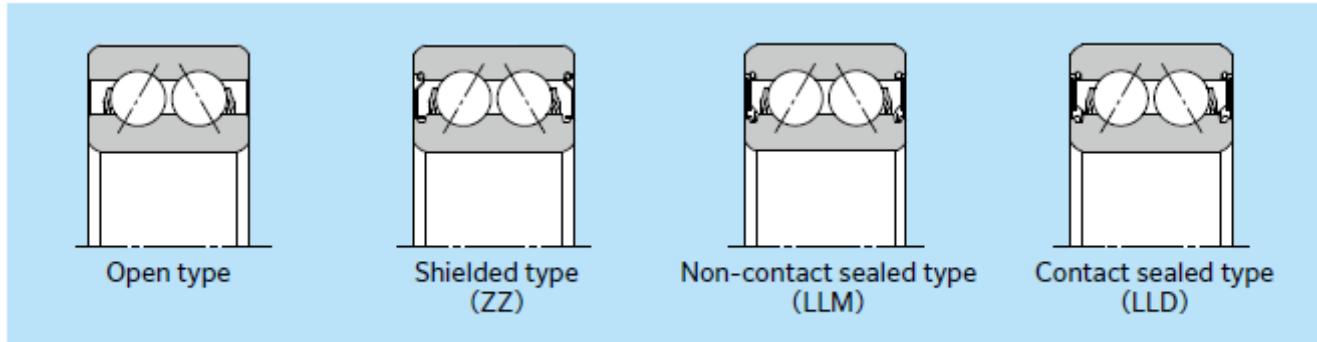


Fig. 4

Table 8.10 (1) Radial internal clearance for duplex angular contact ball bearings Unit: μm

Nominal bearing bore diameter d mm Over Incl.	C1	C2	CN	C3	C4
	Min. Max.				
— 10	3 8	6 12	8 15	15 22	22 30
10 18	3 8	6 12	8 15	15 24	30 40
18 30	3 10	6 12	10 20	20 32	40 55
30 50	3 10	8 14	14 25	25 40	55 75
50 80	3 11	11 17	17 32	32 50	75 95
80 100	3 13	13 22	22 40	40 60	95 120
100 120	3 15	15 30	30 50	50 75	110 140
120 150	3 16	16 33	35 55	55 80	130 170
150 180	3 18	18 35	35 60	60 90	150 200
180 200	3 20	20 40	40 65	65 100	180 240

Note: The clearance group in the table is applied only to contact angles in the table below.

Contact angle symbol	Nominal contact angle	Applicable clearance ²⁾
C	15°	C1, C2
A ¹⁾	30°	C2, CN, C3
B	40°	CN, C3, C4

1) Not indicated for bearing number.

2) For information concerning clearance other than applicable clearance, please contact **NTN** Engineering.

Table 8.10 (2) Radial internal clearance of double row angular contact ball bearings Unit: μm

Nominal bearing bore diameter d mm Over Incl.	C2	CN	C3	C4	C5
	Min. Max.				
10only	0 10	5 15	10 21	16 28	24 36
10 18	1 11	6 16	12 23	19 31	28 40
18 24	1 11	6 16	13 24	21 33	31 43
24 30	1 13	6 19	13 26	21 35	31 45
30 40	2 15	7 22	15 30	24 39	35 50
40 50	2 15	9 24	17 32	28 45	40 57
50 65	0 15	7 24	16 33	28 48	41 61
65 80	1 17	11 31	21 42	34 56	50 74
80 100	3 20	13 36	25 49	40 65	58 67

Table 8.11 Radial internal clearance of bearings for electric motor Unit: μm

Nominal bearing bore diameter d mm Over Incl.	Radial internal clearance CM			
	Deep groove ball bearing Min. Max.	Cylindrical roller bearing Min. Max.		
10 18	4 11	—	—	—
18 24	5 12	—	—	—
24 30	5 12	15	30	30
30 40	9 17	15	30	30
40 50	9 17	20	35	35
50 65	12 22	25	40	40
65 80	12 22	30	45	45
80 100	18 30	35	55	55
100 120	18 30	35	60	60
120 140	24 38	40	65	65
140 160	24 38	50	80	80
160 180	— —	60	90	90
180 200	— —	65	100	100

Note: 1. Suffix CM is added to bearing numbers.

Example: 6205 ZZ CM

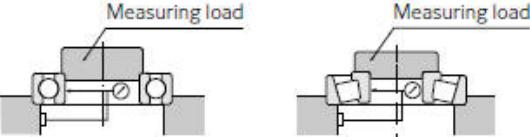
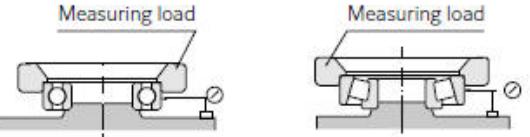
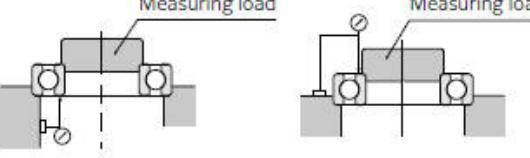
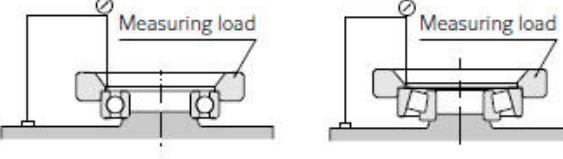
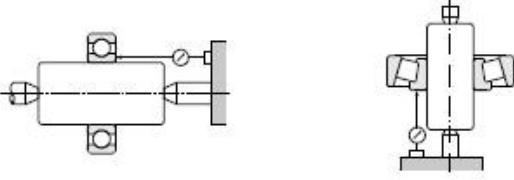
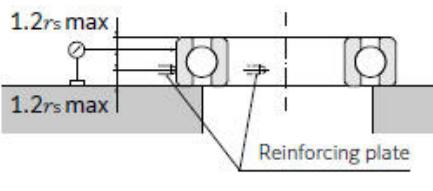
2. Clearance not interchangeable for cylindrical roller bearings.

Parameters you often see on a bearing or bearing spare part drawings:

Terms	Quantifiers	Description
Nominal bore diameter	d	Reference dimension representing the bore diameter size, and reference value with respect to the dimensional difference of the actual bore diameter surface.

Single bore diameter	ds	Distance between two parallel straight lines that are in contact with the intersection line of the actual bearing bore diameter surface and the radial plane.
Deviation of a single bore diameter	Δds	Difference between ds and d (difference of nominal diameter serving as the measured bore and standard).
Mean bore diameter in a single plane	dmp	Arithmetic mean of the maximum and minimum measured bore diameters within one radial plane. In the model figure, in arbitrary radial plane Ai , when the maximum bore diameter is $dsi1$ and the minimum bore diameter is $dsi3$, the value is obtained by $(dsi1 + dsi3)/2$. There is one value for each plane.
Mean bore diameter	dm	Arithmetic mean of the maximum and minimum measured bore diameters obtained from all the cylindrical surfaces. In the model figure, when the maximum measured bore diameter is $ds11$ and the minimum measured bore diameter is $ds23$, which are obtained from the all the planes $A1, A2, \dots, Ai$, the mean bore diameter is obtained by $(ds11 + ds23)/2$. There is one value for one cylindrical surface.
Deviation of mean bore diameter	Δdm	Difference between the mean bore diameter and the nominal bore diameter.
Deviation of mean bore diameter in a single plane	Δdmp	Difference between the arithmetic mean and the nominal bore diameter of the maximum and minimum measured bore diameters within one radial plane. The value is specified in JIS.
Variation of bore diameter in a single plane	$Vdsp$	Difference between the maximum and minimum measured bore diameters within one radial plane. In the model figure, in radial plane $A1$, when the maximum measured bore diameter is $ds11$ and the minimum measured bore diameter is $ds13$, the difference is $Vdsp$ and one value can be obtained for one plane. This characteristic is an index that indicates the roundness. The value is specified in JIS.
Variation of mean bore diameter	$Vdmp$	Difference between the maximum and minimum values of the mean bore diameter within a plane that are obtained from all the planes. A unique value is obtained for each product, and it is near to cylindricity (that is different from geometric cylindricity). The value is specified in JIS.

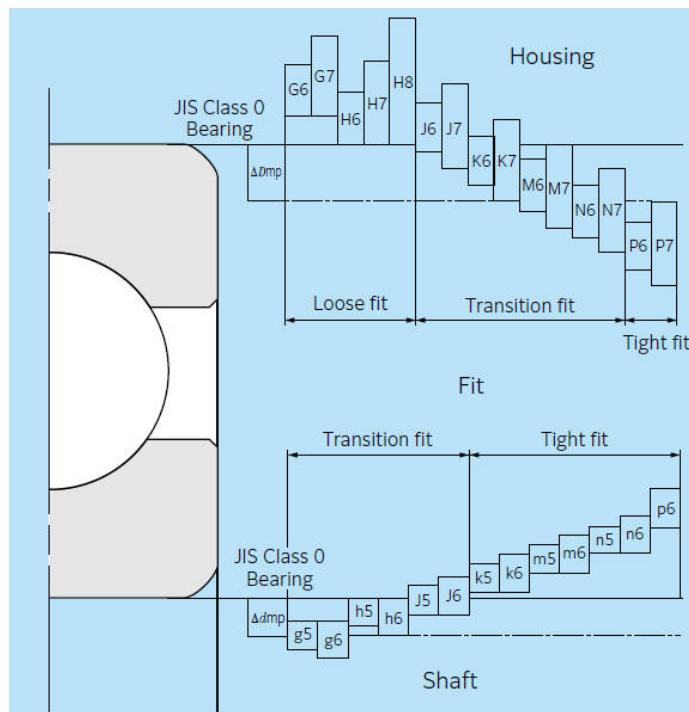
Nominal inner ring width	<i>B</i>	Distance between both theoretical side surfaces of a raceway. This value is a reference dimension that represents the raceway surface (distance between both side surfaces).
Single inner ring width	<i>Bs</i>	Distance between two intersections. The straight is perpendicular to the plane that is in contact with the inner ring reference side and both actual side surfaces. This value represents the actual width dimension of an inner ring.
Deviation of a single inner ring width	ΔBs	Difference between the measured inner ring width and the nominal inner ring width. This value is also the difference between the measured inner ring width dimension and the reference dimension that represents the inner ring width. The value is specified in JIS.
Variation of inner ring width	<i>VBs</i>	Difference between the maximum and minimum measured inner ring widths, which are specified in JIS.
Radial runout of inner ring of assembled bearing	<i>Kia</i>	Difference between the maximum and minimum values of the radial distance between the inner ring bore diameter at each angle position and one fixed point of the outer ring outer diameter surface with respect to radial runout.
Axial runout of inner ring of assembled bearing	<i>Sia</i>	Difference between the maximum and minimum values of the axial distance between the inner ring reference side surface at each angle position and one fixed point of the outer ring outer diameter surface with respect to half the radial distance of the raceway contact diameter from the inner ring central axis and the inner ring of a deep groove ball bearing.

Accuracy characteristics	Measurement methods	
Radial runout of inner ring of assembled bearing (K_{ia})		Radial runout of the inner ring is the difference between the maximum and minimum reading of the measuring device when the inner ring is turned one revolution.
Radial runout of outer ring of assembled bearing (K_{ea})		Radial runout of the outer ring is the difference between the maximum and minimum reading of the measuring device when the outer ring is turned one revolution.
Axial runout of inner ring of assembled bearing (S_{ia})		Axial runout of the inner ring is the difference between the maximum and minimum reading of the measuring device when the inner ring is turned one revolution.
Axial runout of outer ring of assembled bearing (S_{ea})		Axial runout of the outer ring is the difference between the maximum and minimum reading of the measuring device when the outer ring is turned one revolution.
Perpendicularity of inner ring face with respect to the bore (S_d)		The squareness of the inner ring side surface is the difference between the maximum and minimum readings of the measuring device when the inner ring is turned one revolution together with the tapered mandrel.
Perpendicularity of outer ring outside surface with respect to the face (S_D)		The squareness of the outer ring outer diameter surface is the difference between the maximum and minimum readings of the measuring device when the outside ring is turned one revolution along the reinforcing plate.

Bearing Precision Level Definitions and Comparison:

Standard	Applicable standard	Accuracy class					Bearing type
Japanese industrial standard (JIS)	JIS B 1514-1	Class 0, 6	Class 6	Class 5	Class 4	Class 2	Radial bearings
	JIS B 1514-2	Class 0	Class 6	Class 5	Class 4	—	Thrust bearings
International Organization for Standardization (ISO)	ISO 492	Normal class Class 6X	Class 6	Class 5	Class 4	Class 2	Radial bearings
	ISO 199	Normal Class	Class 6	Class 5	Class 4	—	Thrust bearings
	ISO 578	Class 4	—	Class 3	Class 0	Class 00	Tapered roller bearings (Inch series)
	ISO 1224	—	—	Class 5A	Class 4A	—	Precision instrument bearings
Deutsches Institut fur Normung (DIN)	DIN 620	P0	P6	P5	P4	P2	All types
American National Standards Institute (ANSI) American Bearing Manufacturer's Association (ABMA)	ANSI/ABMA Std.20 ¹⁾	ABEC-1 RBEC-1	ABEC-3 RBEC-3	ABEC-5 RBEC-5	ABEC-7	ABEC-9	Radial bearings (excluding tapered roller bearings)
	ANSI/ABMA Std.19.1	Class K	Class N	Class C	Class B	Class A	Tapered roller bearings (Metric series)
	ANSI/ABMA Std.19	Class 4	Class 2	Class 3	Class 0	Class 00	Tapered roller bearings (Inch series)

How to select bearing – housing tolerance range:

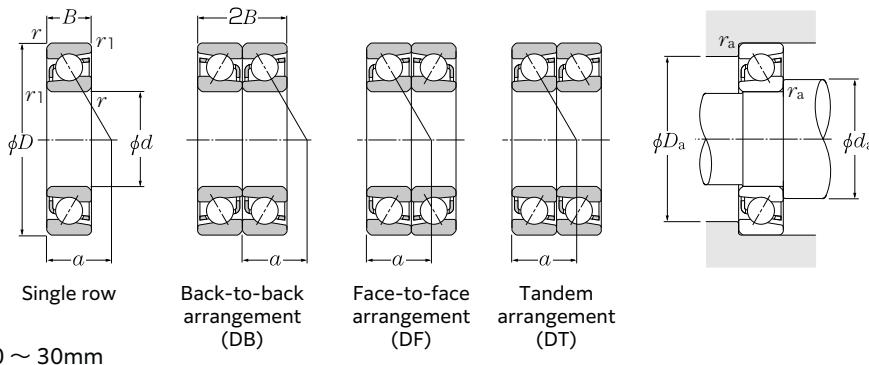


Bearing Damage and Cause

Bearing damage	Damaged parts	Causes							Bearing selection	
		Load	Speed	Excessively large/small interference	Excessively large/small clearance	Swinging/vibration/standstill	Large vibration	High speed/rapid acceleration and deceleration		
		Excessively small load	Excessively large moment	Excessively large impact load/preload	Lubrication method (insufficient)	Lubricant (insufficient/improper quality)	Temperature (heat effect)	Infiltration of bearing by foreign matter (insufficient sealing performance)	Bearing periphery	Handling
Flaking (separation)	Raceway surface/rolling element surface	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
Seizure	Raceway/rolling element/cage	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
Cracks/chips	Raceway/rolling element	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
Cage damage	Rivets break or become loose	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
Rolling path skewing	Raceway surface	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
Smearing/scuffing	Raceway surface/rolling element surface/rib surface/roller end surface	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
Rust/corrosion	Rust on a part of or the entire surface of the rolling element pitch	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
Fretting	Red rust on fitting surface	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	Brinelling indentations form on the raceway of the rolling element pitch	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
Wear	Raceway surface/rolling element surface/rib surface/roller end surface	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
Electrolytic corrosion	Pits form on the raceway. The pits gradually grow into ripples.	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
Dents and scratches	Raceway surface/rolling element surface	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
Creeping	Fitting surface	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
Speckles and discoloration	Raceway surface/rolling element surface	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
Peeling	Raceway surface/rolling element surface	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>

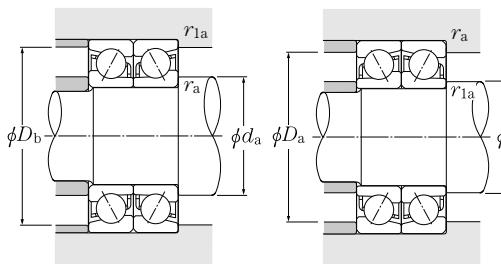
Single and Duplex Angular Contact Ball Bearings

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Single and Duplex Angular Contact Ball Bearings

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Dynamic equivalent radial load

Contact angle e	Single, DT		DB, DF		
	$F_d/F_r \leq e$ X	$F_d/F_r > e$ Y	$F_d/F_r \leq e$ X	$F_d/F_r > e$ Y	
30°	0.80	1	0	0.39	0.76
40°	1.14	1	0	0.35	0.57

Static equivalent radial load

Contact angle	Single, DT		DB, DF	
	X_0	Y_0	X_0	Y_0
30°	0.5	0.33	1	0.66
40°	0.5	0.26	1	0.52

For single and DT arrangement, when $P_{0r} < F_r$ use $P_{0r} = F_r$.

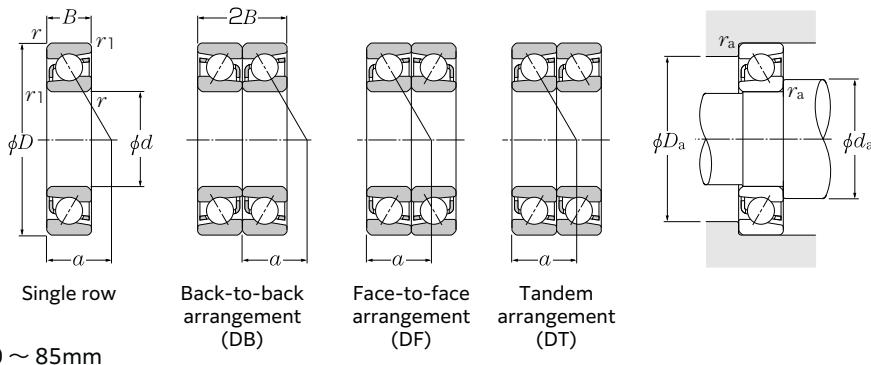
Boundary dimensions				Basic load rating		Fatigue load limit	Allowable speed ¹⁾		Bearing number ²⁾	Load center mm	Mass kg		
d	D	B	$2B$	mm	dynamic	static	Grease lubrication	Oil lubrication	a	Single row (approx.)			
				r_s min ³⁾	r_{ls} min ³⁾	C_r	C_{0r}	min ⁻¹					
10	26	8	16	0.3	0.15	5.10	2.07	0.162	29 000	39 000	7000	9	0.023
	30	9	18	0.6	0.3	6.00	2.74	0.214	28 000	37 000	7200	10.5	0.029
	30	9	18	0.6	0.3	5.50	2.52	0.197	24 000	32 000	7200B	13	0.029
	35	11	22	0.6	0.3	11.2	4.95	0.385	26 000	34 000	7300	12	0.04
	35	11	22	0.6	0.3	10.5	4.60	0.360	22 000	29 000	7300B	15	0.041
12	28	8	16	0.3	0.15	5.60	2.46	0.193	26 000	35 000	7001	10	0.025
	32	10	20	0.6	0.3	8.40	3.95	0.310	25 000	33 000	7201	11.5	0.035
	32	10	20	0.6	0.3	7.75	3.65	0.287	21 000	28 000	7201B	14	0.036
	37	12	24	1	0.6	12.4	5.25	0.410	23 000	30 000	7301	13	0.044
	37	12	24	1	0.6	11.7	4.95	0.385	19 000	26 000	7301B	16.5	0.045
15	32	9	18	0.3	0.15	6.40	3.15	0.246	23 000	31 000	7002	11.5	0.035
	35	11	22	0.6	0.3	10.0	4.70	0.370	22 000	29 000	7202	12.5	0.046
	35	11	22	0.6	0.3	9.25	4.35	0.340	18 000	25 000	7202B	16	0.046
	42	13	26	1	0.6	14.9	7.20	0.560	19 000	26 000	7302	15	0.055
	42	13	26	1	0.6	13.8	6.65	0.520	17 000	22 000	7302B	19	0.057
17	35	10	20	0.3	0.15	7.95	3.85	0.299	21 000	28 000	7003	12.5	0.046
	40	12	24	0.6	0.3	13.2	6.60	0.515	19 000	26 000	7203	14.5	0.064
	40	12	24	0.6	0.3	12.2	6.10	0.480	17 000	22 000	7203B	18	0.066
	47	14	28	1	0.6	17.7	8.65	0.675	18 000	24 000	7303	16	0.107
	47	14	28	1	0.6	16.4	8.05	0.630	15 000	20 000	7303B	20.5	0.109
20	42	12	24	0.6	0.3	10.7	5.60	0.440	19 000	25 000	7004	15	0.08
	47	14	28	1	0.6	16.1	8.40	0.655	17 000	23 000	7204	17	0.1
	47	14	28	1	0.6	14.7	7.70	0.605	15 000	20 000	7204B	21.5	0.102
	52	15	30	1.1	0.6	20.7	10.4	0.815	16 000	21 000	7304	18	0.138
	52	15	30	1.1	0.6	19.2	9.65	0.755	13 000	18 000	7304B	22.5	0.141
25	42	9	18	0.3	0.15	7.90	4.95	0.360	17 000	22 000	7905	14	0.05
	47	12	24	0.6	0.3	11.9	6.85	0.535	16 000	21 000	7005	16.5	0.093
	52	15	30	1	0.6	18.0	10.3	0.805	14 000	19 000	7205	19	0.125
	52	15	30	1	0.6	16.4	9.40	0.740	12 000	16 000	7205B	24	0.129
	62	17	34	1.1	0.6	29.3	15.8	1.24	13 000	17 000	7305	21	0.23
30	42	9	18	0.3	0.15	8.35	5.75	0.395	14 000	19 000	7906	15.5	0.058
	55	13	26	1	0.6	15.4	9.45	0.725	13 000	18 000	7006	19	0.135

¹⁾ This value achieved with machined cages; when pressed cages are used, 80% of this value is acceptable. ²⁾ Bearing numbers appended with the code "B" have a contact angle of 40°; bearings without this code have a contact angle of 30°. ³⁾ Smallest allowable dimension for chamfer dimension r or r_1 .

Note: For bearing series 79 and 70, inner rings are constructed with groove abutments on both sides. Therefore, the inner ring chamfer dimension r_1 is identical to dimension r . Furthermore, the radius r_{1a} of the shaft corner roundness is likewise identical to r_a .

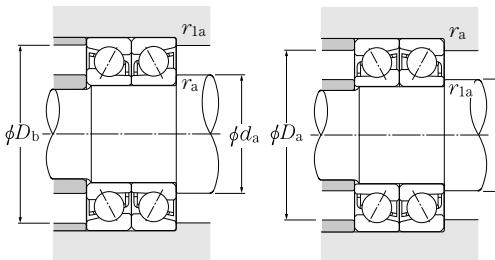
Single and Duplex Angular Contact Ball Bearings

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Single and Duplex Angular Contact Ball Bearings

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Dynamic equivalent radial load

Contact angle e	Single, DT		DB, DF	
	$F_a/F_r \leq e$ X	$F_a/F_r > e$ Y	$F_a/F_r \leq e$ X	$F_a/F_r > e$ Y
30°	0.80	1	0	0.39
40°	1.14	1	0	0.35

Static equivalent radial load

Contact angle	Single, DT		DB, DF	
	X_0	Y_0	X_0	Y_0
30°	0.5	0.33	1	0.66
40°	0.5	0.26	1	0.52

For single and DT arrangement, when $P_{0r} < F_r$ use $P_{0r} = F_r$.

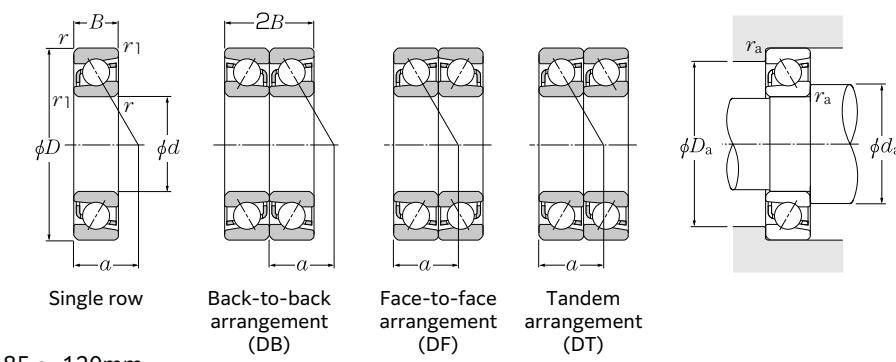
Boundary dimensions				Basic load rating		Fatigue load limit	Allowable speed ¹⁾		Bearing number	Load center	Mass kg		
<i>d</i>	<i>D</i>	<i>B</i>	2 <i>B</i>	<i>r_s</i> min ³⁾	<i>r_{ls}</i> min ³⁾	<i>C_r</i>	dynamic kN	static C _{0r}	Grease lubrication min ⁻¹	Oil lubrication	<i>a</i>	Single row (approx.)	
60	85	13	26	1	0.6	20.0	17.4	1.16	7 800	10 000	7912	27.5	0.23
	95	18	36	1.1	0.6	35.5	28.1	1.99	7 200	9 600	7012	31.5	0.478
	110	22	44	1.5	1	68.5	49.0	3.85	6 600	8 800	7212	36	0.765
	110	22	44	1.5	1	62.0	44.5	3.40	5 700	7 600	7212B	47.5	0.78
	130	31	62	2.1	1.1	109	71.5	5.60	5 900	7 900	7312	43	1.74
	130	31	62	2.1	1.1	99.5	66.0	5.15	5 100	6 800	7312B	56	1.77
65	90	13	26	1	0.6	20.2	18.0	1.20	7 200	9 600	7913	29	0.245
	100	18	36	1.1	0.6	37.5	31.5	2.18	6 700	9 000	7013	33	0.509
	120	23	46	1.5	1	78.0	58.0	4.55	6 100	8 100	7213	38	0.962
	120	23	46	1.5	1	70.5	52.5	3.95	5 200	7 000	7213B	50.5	0.981
	140	33	66	2.1	1.1	123	82.0	6.35	5 500	7 300	7313	46	2.11
	140	33	66	2.1	1.1	113	75.5	5.85	4 700	6 300	7313B	59.5	2.15
70	100	16	32	1	0.6	29.0	26.2	1.74	6 700	9 000	7914	32.5	0.397
	110	20	40	1.1	0.6	47.5	39.5	2.78	6 200	8 300	7014	36	0.705
	125	24	48	1.5	1	84.5	63.5	5.00	5 700	7 600	7214	40	1.09
	125	24	48	1.5	1	76.5	58.0	4.35	4 900	6 500	7214B	53	1.11
	150	35	70	2.1	1.1	138	93.5	6.95	5 100	6 800	7314	49.5	2.56
	150	35	70	2.1	1.1	127	86	6.40	4 400	5 800	7314B	63.5	2.61
75	105	16	32	1	0.6	29.4	27.1	1.80	6 300	8 400	7915	34	0.42
	115	20	40	1.1	0.6	48.5	41.5	2.90	5 800	7 800	7015	37.5	0.745
	130	25	50	1.5	1	87.5	68.5	5.20	5 300	7 100	7215	42.5	1.17
	130	25	50	1.5	1	79.0	62.0	4.50	4 500	6 000	7215B	56	1.19
	160	37	74	2.1	1.1	150	106	7.65	4 800	6 300	7315	52.5	3.07
	160	37	74	2.1	1.1	138	97.5	7.00	4 100	5 400	7315B	68	3.13
80	110	16	32	1	0.6	29.8	28.0	1.86	5 900	7 800	7916	35.5	0.444
	125	22	44	1.1	0.6	59.0	50.5	3.50	5 500	7 300	7016	40.5	0.994
	140	26	52	2	1	98.5	76.0	5.65	5 000	6 600	7216	45	1.39
	140	26	52	2	1	89.0	69.5	4.90	4 300	5 700	7216B	59	1.42
	170	39	78	2.1	1.1	163	119	8.30	4 500	5 900	7316	55.5	3.65
	170	39	78	2.1	1.1	149	109	7.65	3 800	5 100	7316B	72	3.72
85	120	18	36	1.1	0.6	40.0	38.0	2.49	5 500	7 400	7917	38.5	0.628
	130	22	44	1.1	0.6	60.5	53.5	3.60	5 100	6 900	7017	42	1.04
	150	28	56	2	1	110	88.5	6.25	4 700	6 200	7217	48	1.78
	150	28	56	2	1	99.5	80.5	5.45	4 000	5 300	7217B	63.5	1.82

1) This value achieved with machined cages; when pressed cages are used, 80% of this value is acceptable. 2) Bearing numbers appended with the code "B" have a contact angle of 40°; bearings without this code have a contact angle of 30°. 3) Smallest allowable dimension for chamfer dimension r or r_1 .

Note: For bearing series 79 and 70, inner rings are constructed with groove abutments on both sides. Therefore, the inner ring chamfer dimension r_1 is identical to dimension r . Furthermore, the radius r_{1a} of the shaft corner roundness is likewise identical to r_a .

Single and Duplex Angular Contact Ball Bearings

WBW



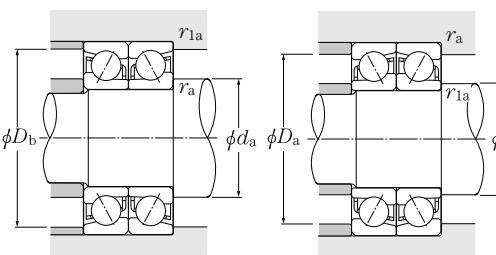
$d = 85 \sim 120\text{mm}$

	Boundary dimensions				Basic load rating		Fatigue load limit	Allowable speed ¹⁾		Bearing number	Load center mm	Mass kg	
	d	D	B	$2B$	r_s mm ³⁾	r_{ls} min ³⁾	dynamic C_r	static C_{0r}	Grease lubrication min ⁻¹	Oil lubrication min ⁻¹			
							kN	kN	Single row (approx.)				
85	180	41	82	3	1.1	176	133	9.00	4 200	5 600	7317	59	4.34
	180	41	82	3	1.1	161	122	8.30	3 600	4 800	7317B	76	4.43
	125	18	36	1.1	0.6	39.5	38.0	2.42	5 200	7 000	7918	40	0.658
	140	24	48	1.5	1	72.0	63.5	4.15	4 900	6 500	7018	45	1.35
	160	30	60	2	1	130	103	7.20	4 400	5 900	7218	51	2.18
	160	30	60	2	1	118	94.0	6.30	3 800	5 000	7218B	67.5	2.22
90	190	43	86	3	1.1	189	147	9.70	4 000	5 300	7318	62	5.06
	190	43	86	3	1.1	173	135	8.95	3 400	4 500	7318B	80.5	5.16
	130	18	36	1.1	0.6	41.5	40.5	2.54	5 000	6 600	7919	41.5	0.688
	145	24	48	1.5	1	74.0	67.0	4.25	4 600	6 100	7019	46.5	1.41
	170	32	64	2.1	1.1	148	118	8.05	4 100	5 500	7219	54.5	2.67
	170	32	64	2.1	1.1	134	107	7.00	3 500	4 700	7219B	71.5	2.72
95	200	45	90	3	1.1	202	162	10.5	3 700	5 000	7319	65	5.89
	200	45	90	3	1.1	185	149	9.60	3 200	4 200	7319B	84.5	6
	140	20	40	1.1	0.6	53.0	52.5	3.20	4 700	6 200	7920	44.5	0.934
	150	24	48	1.5	1	75.5	70.5	4.35	4 400	5 800	7020	48	1.47
	180	34	68	2.1	1.1	159	126	8.30	3 900	5 200	7220	57.5	3.2
	180	34	68	2.1	1.1	144	114	7.30	3 400	4 500	7220B	76	3.26
100	215	47	94	3	1.1	230	193	12.0	3 500	4 700	7320	69	7.18
	215	47	94	3	1.1	211	178	11.1	3 000	4 000	7320B	89.5	7.32
	145	20	40	1.1	0.6	54.0	54.5	3.25	4 400	5 900	7921	46	0.972
	160	26	52	2	1	88.5	81.5	4.95	4 100	5 500	7021	51.5	1.86
	190	36	72	2.1	1.1	173	142	9.10	3 700	5 000	7221	60.5	3.79
	190	36	72	2.1	1.1	157	129	8.05	3 200	4 300	7221B	80	3.87
105	225	49	98	3	1.1	244	210	12.8	3 400	4 500	7321	72	8.2
	225	49	98	3	1.1	224	194	11.8	2 900	3 800	7321B	93.5	8.36
	150	20	40	1.1	0.6	54.5	56.0	3.25	4 200	5 700	7922	47.5	1.01
	170	28	56	2	1	102	93.0	5.50	3 900	5 300	7022	54.5	2.3
	200	38	76	2.1	1.1	188	158	9.95	3 500	4 700	7222	64	4.45
	200	38	76	2.1	1.1	170	144	8.80	3 000	4 000	7222B	84	4.54
110	240	50	100	3	1.1	273	246	14.5	3 200	4 300	7322	76	9.6
	240	50	100	3	1.1	250	226	13.3	2 700	3 700	7322B	99	9.8
	165	22	44	1.1	0.6	67.5	69.5	3.90	3 900	5 200	7924	52	1.66
	165	22	44	1.1	0.6	67.5	69.5	3.90	3 900	5 200	7924	52	1.66
	165	22	44	1.1	0.6	67.5	69.5	3.90	3 900	5 200	7924	52	1.66

¹⁾ This value achieved with machined cages; when pressed cages are used, 80% of this value is acceptable. ²⁾ Bearing numbers appended with the code "B" have a contact angle of 40°; bearings without this code have a contact angle of 30°. ³⁾ Smallest allowable dimension for chamfer dimension r or r_1 .

Single and Duplex Angular Contact Ball Bearings

WBW



Dynamic equivalent radial load

$$P_{Fr} = X F_r + Y F_a$$

Single, DT		DB, DF	
$F_r/F_d \leq e$	$F_r/F_d > e$	$F_r/F_d \leq e$	$F_r/F_d > e$
X	Y	X	Y
0.80	1	0.39	0.76

30°		40°	
0.80	1	0.35	0.57
1.01	1	1.09	0.93

Static equivalent radial load

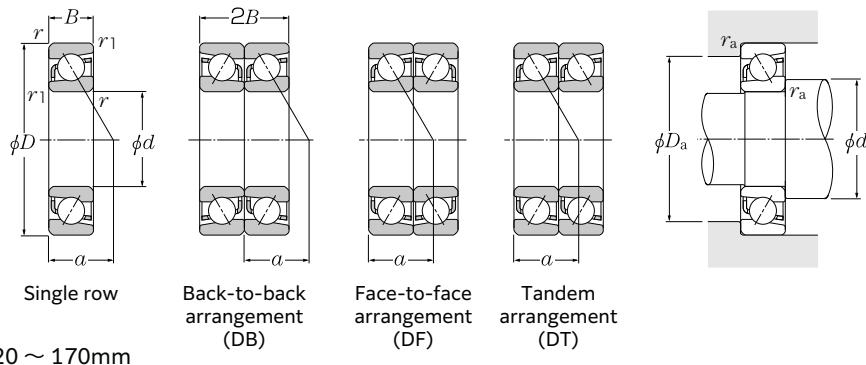
$$P_{Or} = X_0 F_r + Y_0 F_a$$

Single, DT		DB, DF	
X_0	Y_0	X_0	Y_0
0.5	0.33	1	0.66
0.5	0.26	1	0.52

For single and DT arrangement, when $P_{Or} < F_r$ use $P_{Or} = F_r$.

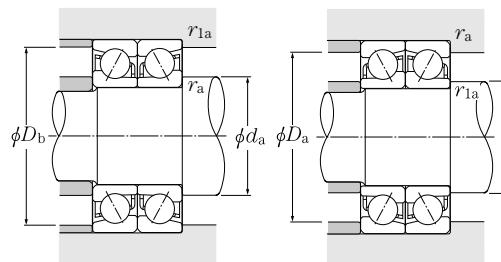
Single and Duplex Angular Contact Ball Bearings

WBW



Single and Duplex Angular Contact Ball Bearings

WBW



Dynamic equivalent radial load

$$P_r = X F_r + Y F_a$$

Contact angle e	Single, DT		DB, DF	
	$F_d / F_r \leq e$ X	$F_d / F_r > e$ Y	$F_d / F_r \leq e$ X	$F_d / F_r > e$ Y
30°	0.80	1	0	0.39
40°	1.14	1	0	0.35

Static equivalent radial load

$$P_{0r} = X_0 F_r + Y_0 F_a$$

Contact angle	Single, DT		DB, DF	
	X_0	Y_0	X_0	Y_0
30°	0.5	0.33	1	0.66
40°	0.5	0.26	1	0.52

For single and DT arrangement, when $P_{0r} < F_r$ use $P_{0r} = F_r$.

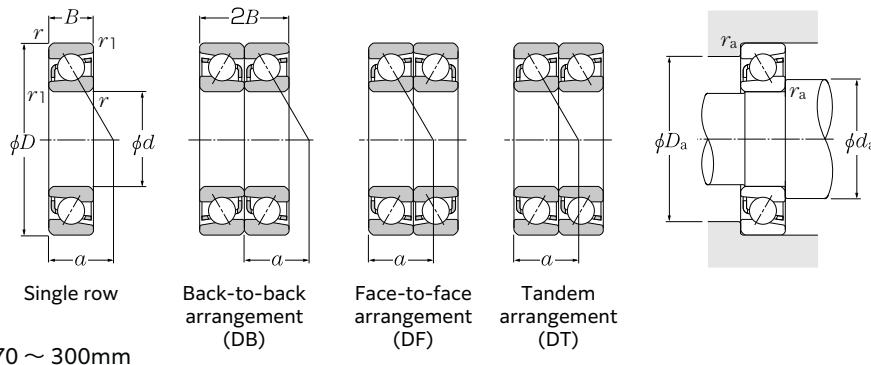
Basic load rating dynamic (duplex) kN C_r	Basic load rating static kN C_{0r}	Allowable speed ¹⁾ (duplex) min ⁻¹		Bearing number			Installation-related dimensions					
		Grease lubrication	Oil lubrication	DB	DF	DT	d_a mm. Min.	D_b mm. Max.	r_{as} mm. Max.	r_{1as} mm. Max.		
169	197	2 900	3 800	DB	DF	DT	130	170	174.5	2	1	
330	355	2 600	3 400	DB	DF	DT	132	203	208	2	1	
298	325	2 300	3 000	DB	DF	DT	132	203	208	2	1	
445	505	2 300	3 100	DB	DF	DT	134	246	253	2.5	1	
405	460	2 000	2 700	DB	DF	DT	134	246	253	2.5	1	
135	175	2 800	3 800	DB	DF	DT	138.5	171.5	174.5	1.5	1	
211	251	2 600	3 500	DB	DF	DT	140	190	194.5	2	1	
355	395	2 400	3 100	DB	DF	DT	144	216	223	2.5	1	
320	360	2 100	2 700	DB	DF	DT	144	216	223	2.5	1	
490	585	2 100	2 800	DB	DF	DT	148	262	271.5	3	1.5	
450	535	1 900	2 500	DB	DF	DT	148	262	271.5	3	1.5	
136	180	2 600	3 500	DB	DF	DT	148.5	181.5	184.5	1.5	1	
215	265	2 400	3 300	DB	DF	DT	150	200	204.5	2	1	
365	430	2 200	2 900	DB	DF	DT	154	236	243	2.5	1	
330	390	1 900	2 500	DB	DF	DT	154	236	243	2.5	1	
540	670	2 000	2 600	DB	DF	DT	158	282	291.5	3	1.5	
495	615	1 700	2 300	DB	DF	DT	158	282	291.5	3	1.5	
175	234	2 400	3 300	DB	DF	DT	160	200	204.5	2	1	
246	305	2 300	3 000	DB	DF	DT	162	213	218	2	1	
420	515	2 000	2 700	DB	DF	DT	164	256	263	2.5	1	
375	470	1 800	2 400	DB	DF	DT	164	256	263	2.5	1	
595	765	1 800	2 400	DB	DF	DT	168	302	311.5	3	1.5	
540	700	1 600	2 100	DB	DF	DT	168	302	311.5	3	1.5	
177	241	2 300	3 000	DB	DF	DT	170	210	214.5	2	1	
279	355	2 100	2 800	DB	DF	DT	172	228	233	2	1	
475	615	1 900	2 500	DB	DF	DT	174	276	283	2.5	1	
430	555	1 600	2 200	DB	DF	DT	174	276	283	2.5	1	
625	845	1 700	2 300	DB	DF	DT	178	322	331.5	3	1.5	
570	770	1 500	2 000	DB	DF	DT	178	322	331.5	3	1.5	
183	257	2 100	2 800	DB	DF	DT	180	220	224.5	2	1	
335	430	2 000	2 600	DB	DF	DT	182	248	253	2	1	
530	715	1 800	2 400	DB	DF	DT	188	292	301.5	3	1.5	
480	650	1 500	2 100	DB	DF	DT	188	292	301.5	3	1.5	
700	970	1 600	2 100	DB	DF	DT	188	342	351.5	3	1.5	

1) Bearing numbers appended with the code "B" have a contact angle of 40°; bearings without this code have a contact angle of 30°.

2) Smallest allowable dimension for chamfer dimension r or r_1 .

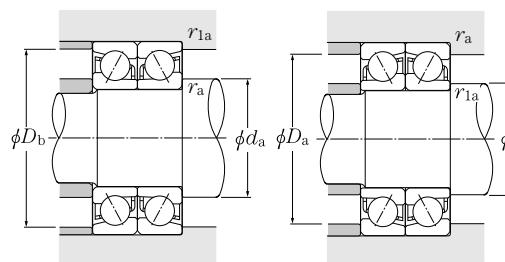
Single and Duplex Angular Contact Ball Bearings

WBW



Single and Duplex Angular Contact Ball Bearings

WBW



Dynamic equivalent radial load
 $P_r = X F_r + Y F_a$

Contact angle e	Single, DT		DB, DF	
	$F_d / F_r \leq e$ X	$F_d / F_r > e$ Y	$F_d / F_r \leq e$ X	$F_d / F_r > e$ Y
30°	0.80	1	0	0.39
40°	1.14	1	0	0.35
		0.57	0.57	0.57
		1	1	0.93

Static equivalent radial load
 $P_{0r} = X_0 F_r + Y_0 F_a$

Contact angle	Single, DT		DB, DF	
	X_0	Y_0	X_0	Y_0
30°	0.5	0.33	1	0.66
40°	0.5	0.26	1	0.52

For single and DT arrangement, when $P_{0r} < F_r$ use $P_{0r} = F_r$.

d	Boundary dimensions	Basic load rating		Fatigue load limit	Allowable speed	Bearing number	Load center	Mass kg
		dynamic mm	static kN					
		D	B	$2B$	r_s min ²⁾	r_s min ²⁾	C_r	C_{0r}
170	360	72	144	4	1.5	395	445	21.3
	250	33	66	2	1	145	163	7.40
	280	46	92	2.1	1.1	242	266	12.3
	320	52	104	4	1.5	340	385	18.6
	320	52	104	4	1.5	305	350	16.1
	380	75	150	4	1.5	455	535	24.9
180	380	75	150	4	1.5	415	490	22.8
	260	33	66	2	1	147	169	7.45
	290	46	92	2.1	1.1	248	280	12.6
	340	55	110	4	1.5	335	390	17.9
	340	55	110	4	1.5	300	355	15.5
	400	78	156	5	2	475	585	26.6
190	400	78	156	5	2	430	535	24.0
	280	38	76	2.1	1.1	205	231	9.90
	310	51	102	2.1	1.1	279	325	14.3
	360	58	116	4	1.5	375	450	20.2
	360	58	116	4	1.5	335	410	17.6
	420	80	160	5	2	500	610	27.0
200	420	80	160	5	2	455	555	24.7
	280	38	76	2.1	1.1	207	239	9.85
	310	51	102	2.1	1.1	279	325	14.3
	360	58	116	4	1.5	375	450	20.2
	360	58	116	4	1.5	335	410	17.6
	420	80	160	5	2	500	610	27.0
220	300	38	76	2.1	1.1	207	239	9.85
	320	38	76	2.1	1.1	213	255	10.1
	360	46	92	2.1	1.1	285	375	14.1
	380	46	92	2.1	1.1	289	385	14.1
	420	56	112	3	1.1	360	520	18.2
	300	38	76	2.1	1.1	207	239	9.85

Basic load rating	Allowable speed	Bearing number	Installation-related dimensions								
			dynamic (duplex) Grease lubrication	static (duplex) Oil lubrication	DB	DF	DT	d_a mm	D_b mm		
640	890	1 400	1 800	DB	DF	DT	188	342	351.5	3	1.5
236	325	2 000	2 700	DB	DF	DT	190	240	244.5	2	1
395	530	1 900	2 500	DB	DF	DT	192	268	273	2	1
550	770	1 700	2 200	DB	DF	DT	198	302	311.5	3	1.5
495	700	1 400	1 900	DB	DF	DT	198	302	311.5	3	1.5
735	1 070	1 500	2 000	DB	DF	DT	198	362	371.5	3	1.5
670	975	1 300	1 700	DB	DF	DT	198	362	371.5	3	1.5
239	335	1 900	2 500	DB	DF	DT	200	250	254.5	2	1
405	560	1 800	2 300	DB	DF	DT	202	278	283	2	1
545	780	1 600	2 100	DB	DF	DT	208	322	331.5	3	1.5
490	705	1 400	1 800	DB	DF	DT	208	322	331.5	3	1.5
770	1 170	1 400	1 900	DB	DF	DT	212	378	390	4	2
700	1 070	1 200	1 600	DB	DF	DT	212	378	390	4	2
335	465	1 800	2 400	DB	DF	DT	212	268	273	2	1
455	650	1 700	2 200	DB	DF	DT	212	298	303	2	1
605	900	1 500	2 000	DB	DF	DT	218	342	351.5	3	1.5
545	815	1 300	1 700	DB	DF	DT	218	342	351.5	3	1.5
810	1 220	1 300	1 800	DB	DF	DT	222	398	410	4	2
740	1 110	1 200	1 500	DB	DF	DT	222	398	410	4	2
335	475	1 600	2 100	DB	DF	DT	232	288	293	2	1
345	510	1 500	1 900	DB	DF	DT	252	308	313	2	1
465	750	1 300	1 800	DB	DF	DT	272	348	353	2	1
470	775	1 200	1 600	DB	DF	DT	292	368	373	2	1
590	1 040	1 100	1 500	DB	DF	DT	314	406	413	2.5	1

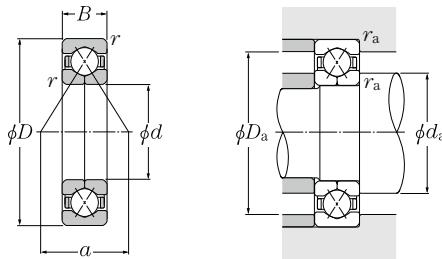
1) Bearing numbers appended with the code "B" have a contact angle of 40°; bearings without this code have a contact angle of 30°.

2) Smallest allowable dimension for chamfer dimension r or r_1 .

● Four-Point Contact Ball Bearings

WBW

QJ type



Dynamic equivalent axial load
 $P_a = F_a$
Static equivalent axial load
 $P_{0a} = F_a$

$d \sim 30 \sim 90\text{mm}$

	Boundary dimensions			Basic load rating		Fatigue load limit	Allowable speed		Bearing number	Installation-related dimensions			Load center	Mass
	d	D	B	$r_s \text{ min}^{-1}$	C _a	C _{0a}	Grease lubrication	Oil lubrication	min ⁻¹	d _a	D _a	r _{as}	mm	kg
30	72	19	1.1	44.0	57.5	2.46	8 000	11 000	QJ306	37	65	1	30	0.42
35	80	21	1.5	55.0	73.0	3.15	7 000	9 300	QJ307	43.5	71.5	1.5	33	0.57
40	80	18	1.1	49.0	70.5	3.05	6 900	9 200	QJ208	47	73	1	34.5	0.45
	90	23	1.5	67.0	91.5	3.95	6 200	8 200	QJ308	48.5	81.5	1.5	37.5	0.78
45	85	19	1.1	55.0	81.0	3.50	6 200	8 200	QJ209	52	78	1	37.5	0.52
	100	25	1.5	87.0	121	5.20	5 500	7 400	QJ309	53.5	91.5	1.5	42	1.05
50	90	20	1.1	57.5	89.0	3.80	5 600	7 500	QJ210	57	83	1	40.5	0.603
	110	27	2	102	145	6.20	5 000	6 700	QJ310	60	100	2	46	1.38
55	100	21	1.5	71.0	112	4.80	5 100	6 800	QJ211	63.5	91.5	1.5	44.5	0.78
	120	29	2	118	170	7.30	4 600	6 100	QJ311	65	110	2	50.5	1.76
60	110	22	1.5	86.0	138	5.90	4 700	6 300	QJ212	68.5	101.5	1.5	49	0.98
	130	31	2.1	135	198	8.50	4 200	5 700	QJ312	72	118	2	55	2.18
65	120	23	1.5	93.5	153	6.55	4 400	5 800	QJ213	73.5	111.5	1.5	53.5	1.24
	140	33	2.1	153	228	9.70	3 900	5 200	QJ313	77	128	2	59	2.7
70	125	24	1.5	102	168	7.15	4 000	5 400	QJ214	78.5	116.5	1.5	56.5	1.36
	150	35	2.1	172	260	10.7	3 600	4 800	QJ314	82	138	2	63.5	3.27
75	130	25	1.5	106	183	7.55	3 800	5 000	QJ215	83.5	121.5	1.5	59	1.53
	160	37	2.1	187	294	11.7	3 400	4 500	QJ315	87	148	2	68	3.9
80	140	26	2	124	217	8.65	3 500	4 700	QJ216	90	130	2	63.5	1.83
	170	39	2.1	202	330	12.7	3 200	4 200	QJ316	92	158	2	72	4.64
85	150	28	2	139	252	9.65	3 300	4 400	QJ217	95	140	2	68	2.3
	180	41	3	218	370	13.8	3 000	4 000	QJ317	99	166	2.5	76.5	5.43
90	160	30	2	164	293	11.1	3 100	4 200	QJ218	100	150	2	72	2.76
	190	43	3	235	410	14.8	2 800	3 800	QJ318	104	176	2.5	81	6.31

1) Smallest allowable dimension for chamfer dimension r .

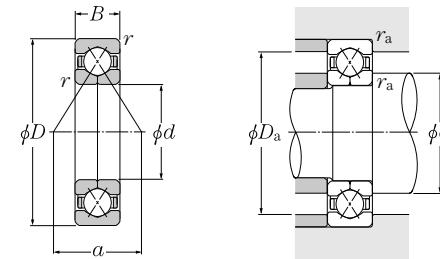
Note: 1. These bearings are also manufactured with a slot in the chamfer section of the outer ring to stop whirling.

2. This bearing is widely used in applications where the only type of load is axial. When considering it for use where radial loads are applied, consult NTN Engineering.

● Four-Point Contact Ball Bearings

WBW

QJ type



Dynamic equivalent axial load
 $P_a = F_a$
Static equivalent axial load
 $P_{0a} = F_a$

$d \sim 95 \sim 120\text{mm}$

	Boundary dimensions			Basic load rating		Fatigue load limit	Allowable speed		Bearing number	Installation-related dimensions			Load center	Mass
	d	D	B	$r_s \text{ min}^{-1}$	C _a	C _{0a}	Grease lubrication	Oil lubrication	min ⁻¹	d _a	D _a	r _{as}	mm	kg
95	170	32	2.1	186	335	12.4	3 000	3 900	QJ219	107	158	2	76.5	3.35
	200	45	3	251	450	16.0	2 700	3 500	QJ319	109	186	2.5	85	7.41
100	180	34	2.1	200	355	12.9	2 800	3 700	QJ220	112	168	2	81	4.02
	215	47	3	302	585	20.0	2 500	3 400	QJ320	114	201	2.5	91	9.14
105	190	36	2.1	218	400	14.2	2 700	3 600	QJ221	117	178	2	85	4.75
	225	49	3	303	585	19.6	2 400	3 200	QJ321	119	211	2.5	95.5	10.4
110	200	38	2.1	236	450	15.5	2 500	3 400	QJ222	122	188	2	89.5	5.62
	240	50	3	338	680	22.1	2 300	3 100	QJ322	124	226	2.5	101	12
120	215	40	2.1	266	540	17.7	2 300	3 100	QJ224	132	203	2	96.5	6.75
	260	55	3	359	765	23.8	2 100	2 800	QJ324	134	246	2.5	110	15.9

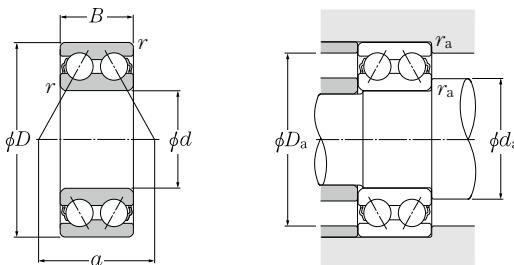
1) Smallest allowable dimension for chamfer dimension r .

Note: 1. These bearings are also manufactured with a slot in the chamfer section of the outer ring to stop whirling.

2. This bearing is widely used in applications where the only type of load is axial. When considering it for use where radial loads are applied, consult NTN Engineering.

Double Row Angular Contact Ball Bearings

WBW



Dynamic equivalent radial load
 $P_r = X F_r + Y F_a$

e	$\frac{F_a}{F_r} \leq e$		$\frac{F_a}{F_r} > e$	
	X	Y	X	Y
0.68	1	0.92	0.67	1.41

Static equivalent radial load
 $P_{0r} = F_r + 0.76 F_a$

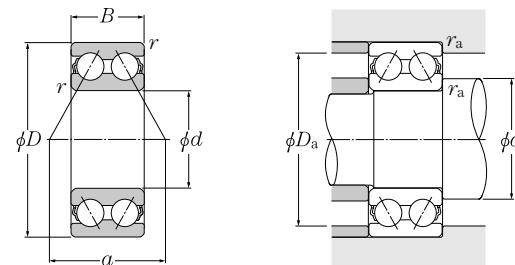
d 10 ~ 65mm

d	D	B	$r_s \text{ min}^{-1}$	Boundary dimensions		Basic load rating dynamic kN	C_r	Fatigue load limit kN	C_{0r}	Allowable speed min ⁻¹	Bearing number	Installation-related dimensions			Load center mm	Mass kg	
				mm	Grease lubrication							mm	mm	mm			
d_a	Min.	Max.	D_a	Max.	Max.	r_{as}	a	(approx.)									
10	30	14.3	0.6	7.15	3.90	0.230	17 000	22 000	5200S	15	25	0.6	14.5	0.05			
12	32	15.9	0.6	10.5	5.80	0.350	15 000	20 000	5201S	17	27	0.6	16.7	0.06			
15	35	15.9	0.6	11.7	7.05	0.420	13 000	17 000	5202S	20	30	0.6	18.3	0.07			
	42	19	1	17.6	10.2	0.620	11 000	15 000	5302S	21	36	1	22	0.13			
17	40	17.5	0.6	14.6	9.05	0.540	11 000	15 000	5203S	22	35	0.6	20.8	0.1			
	47	22.2	1	21.0	12.6	0.770	10 000	13 000	5303S	23	41	1	25	0.18			
20	47	20.6	1	19.6	12.4	0.750	10 000	13 000	5204S	26	41	1	24.3	0.16			
	52	22.2	1.1	24.6	15.0	0.930	9 000	12 000	5304S	27	45	1	26.7	0.22			
25	52	20.6	1	21.3	14.7	0.880	8 500	11 000	5205S	31	46	1	26.8	0.18			
	62	25.4	1.1	32.5	20.7	1.30	7 500	10 000	5305S	32	55	1	31.8	0.35			
30	62	23.8	1	29.6	21.1	1.30	7 100	9 500	5206S	36	56	1	31.6	0.3			
	72	30.2	1.1	40.5	28.1	1.70	6 300	8 500	5306S	37	65	1	36.5	0.57			
35	72	27	1.1	39.0	28.7	1.70	6 300	8 000	5207S	42	65	1	36.6	0.46			
	80	34.9	1.5	51.0	36.0	2.20	5 600	7 500	5307S	44	71	1.5	41.6	0.76			
40	80	30.2	1.1	44.0	33.5	2.00	5 600	7 100	5208S	47	73	1	41.5	0.62			
	90	36.5	1.5	56.5	41.0	2.50	5 300	6 700	5308S	49	81	1.5	45.5	1.03			
45	85	30.2	1.1	49.5	38.0	2.30	5 000	6 700	5209S	52	78	1	43.4	0.67			
	100	39.7	1.5	68.5	51.0	3.10	4 500	6 000	5309S	54	91	1.5	50.6	1.37			
50	90	30.2	1.1	53.0	43.5	2.70	4 800	6 000	5210S	57	83	1	45.9	0.72			
	110	44.4	2	81.5	61.5	3.80	4 300	5 600	5310S	60	100	2	55.6	1.84			
55	100	33.3	1.5	56.0	49.0	3.00	4 300	5 600	5211S	64	91	1.5	50.1	1.01			
	120	49.2	2	95.0	73.0	4.50	3 800	5 000	5311S	65	110	2	60.6	2.4			
60	110	36.5	1.5	69.0	62.0	3.80	3 800	5 000	5212S	69	101	1.5	56.5	1.33			
	130	54	2.1	125	98.5	6.00	3 400	4 500	5312S	72	118	2	69.2	2.92			
65	120	38.1	1.5	76.5	69.0	4.20	3 600	4 500	5213S	74	111	1.5	59.7	1.71			
	140	58.7	2.1	142	113	7.00	3 200	4 300	5313S	77	128	2	72.8	3.67			

1) Smallest allowable dimension for chamfer dimension r .

Double Row Angular Contact Ball Bearings

WBW



Dynamic equivalent radial load
 $P_r = X F_r + Y F_a$

e	$\frac{F_a}{F_r} \leq e$		$\frac{F_a}{F_r} > e$	
	X	Y	X	Y
0.68	1	0.92	0.67	1.41

Static equivalent radial load
 $P_{0r} = F_r + 0.76 F_a$

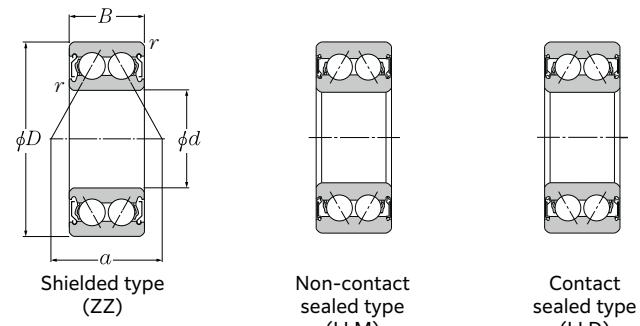
d 70 ~ 85mm

d	D	B	$r_s \text{ min}^{-1}$	Boundary dimensions		Basic load rating dynamic kN	C_r	Fatigue load limit kN	C_{0r}	Allowable speed min ⁻¹	Installation-related dimensions			Load center mm	Mass kg		
				mm	Grease lubrication						mm	mm	mm				
d_a	Min.	Max.	D_a	Max.	Max.	r_{as}	a	(approx.)									
70	125	39.7	1.5	94.0	82.0	5.00	3 400	4 500	5214S	79	116	1.5	63.8	1.75			
	150	63.5	2.1	159	128	7.90	3 000	3 800	5314S	82	138	2	78.3	4.55			
75	130	41.3	1.5	93.5	83.0	5.10	3 200	4 300	5215S	84	121	1.5	66.1	1.88			
	140	44.4	2	99.0	93.0	5.70	3 000	3 800	5216S	90	130	2	69.6	2.51			
85	150	49.2	2	116	110	6.70	2 800	3 600	5217S	95	140	2	75.3	3.16			

1) Smallest allowable dimension for chamfer dimension r .

Sealed and Shielded Double Row Angular Contact Ball Bearings

WBW



d 10 ~ 40mm

d	Boundary dimensions mm	Basic load rating		Fatigue load limit kN	Allowable speed min ⁻¹			Bearing number ²⁾		
		dynamic kN	static kN		Grease lubrication ZZ, LLM Z, LM	Oil lubrication Z, LM	LLD, LD	Shielded type	Non-contact sealed type	Contact sealed type
10	30 14.3 0.6	7.15	3.90	0.230	17 000	22 000	15 000	5200SCZZ	LLM	LLD
12	32 15.9 0.6	8.50	5.30	0.310	15 000	20 000	12 000	5201SCZZ	LLM	LLD
15	35 15.9 0.6	8.50	5.30	0.310	13 000	17 000	12 000	5202SCZZ	LLM	LLD
17	40 17.5 0.6	12.7	8.30	0.490	11 000	15 000	10 000	5203SCZZ	LLM	LLD
	47 22.2 1	19.6	12.4	0.750	10 000	13 000	9 500	5303SCZZ	LLM	LLD
20	47 20.6 1	15.9	10.7	0.640	10 000	13 000	9 000	5204SCZZ	LLM	LLD
25	52 20.6 1	16.9	12.3	0.740	8 500	11 000	7 500	5205SCZZ ³⁾	LLM	LLD
	62 25.4 1.1	25.2	18.2	1.10	7 500	10 000	6 300	5305SCZZ	LLM	LLD
30	62 23.8 1	25.2	18.2	1.10	7 100	9 500	6 300	5206SCZZ	LLM	LLD
	72 30.2 1.1	39.0	28.7	1.70	6 300	8 500	5 300	5306SCZZ	LLM	LLD
35	72 27.0 1.1	34.0	25.3	1.50	6 300	8 500	5 300	5207SCZZ	LLM	LLD
	80 34.9 1.5	44.0	33.5	2.00	5 600	7 500	4 800	5307SCZZ	LLM	LLD
40	80 30.2 1.1	36.5	29.0	1.70	5 600	7 100	4 800	5208SCZZ ³⁾	LLM	LLD
	90 36.5 1.5	49.5	38.0	2.30	5 300	6 700	4 500	5308SCZZ	LLM	LLD

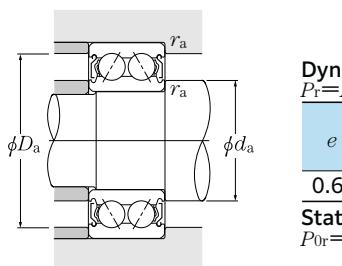
1) Smallest allowable dimension for chamfer dimension *r*.

2) This bearing number is for double sealed and double shielded type bearings, but single sealed and single shielded types are also available.

3) Resin formed cage is standard for 5205SC and 5208SC.

Sealed and Shielded Double Row Angular Contact Ball Bearings

WBW



Dynamic equivalent radial load
 $P_r = X F_r + Y F_a$

<i>e</i>	$\frac{F_a}{F_r} \leq e$		$\frac{F_a}{F_r} > e$	
	<i>X</i>	<i>Y</i>	<i>X</i>	<i>Y</i>
0.68	1	0.92	0.67	1.41

Static equivalent radial load
 $P_{0r} = F_r + 0.76 F_a$

Installation-related dimensions mm	Load center			
	<i>d_a</i> Min.	<i>D_a</i> Max.	<i>r_{as}</i> Max.	<i>a</i>
14	15.5	26	0.6	14.5
16	19	28	0.6	16.3
19	19	31	0.6	16.3
21	23.5	36	0.6	20.1
23	25.5	41	1	24.3
26	26.5	41	1	23
31	32	46	1	25.4
32	38.5	55	1	30.9
36	38.5	56	1	30.9
37	44.5	65	1	36.6
42	45	65	1	36.3
44	50.5	71	1.5	41.5
47	50.5	73	1	39.4
49	53	81	1.5	43